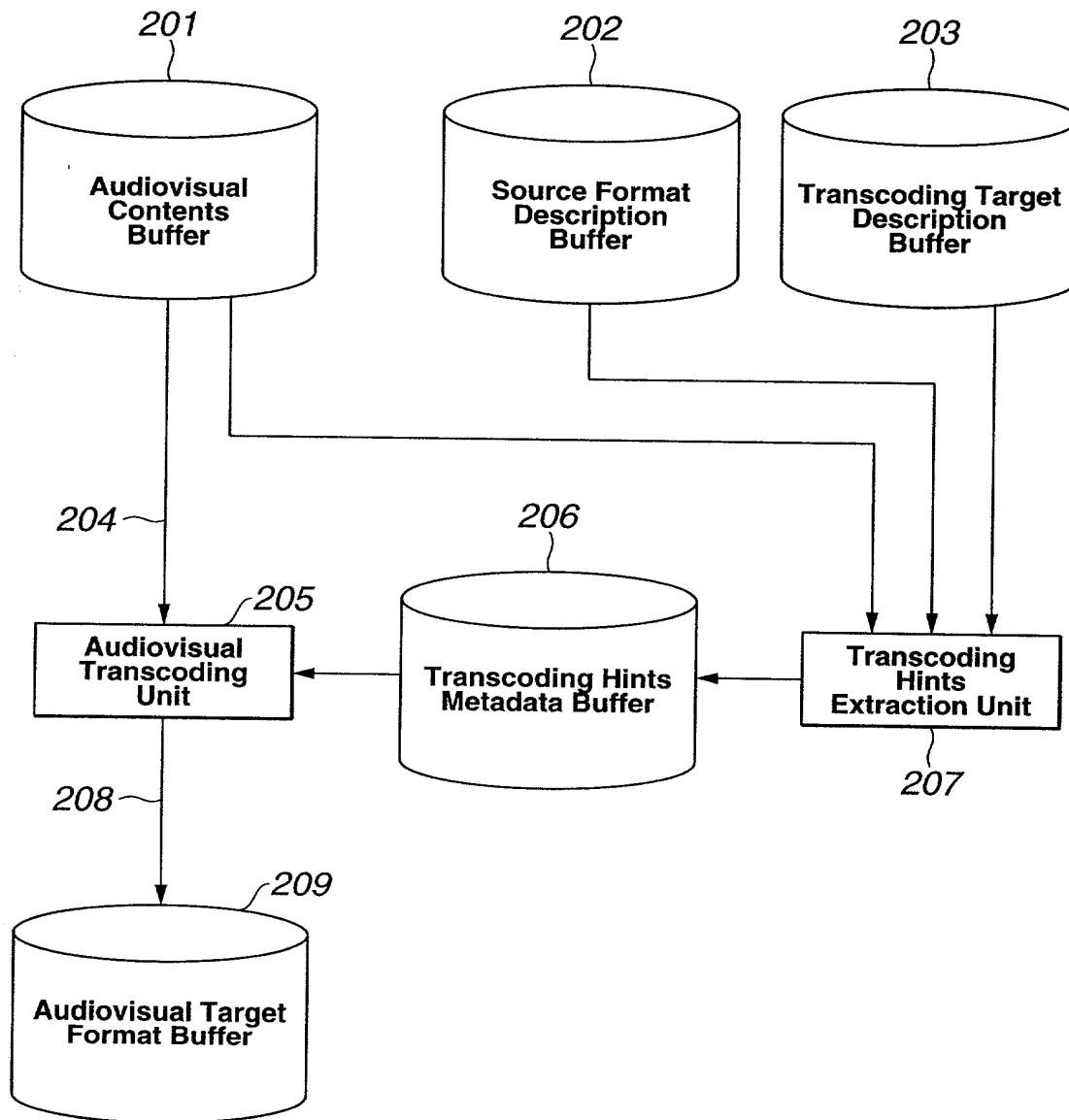


FIG.1

2/13

**FIG.2**

3/13

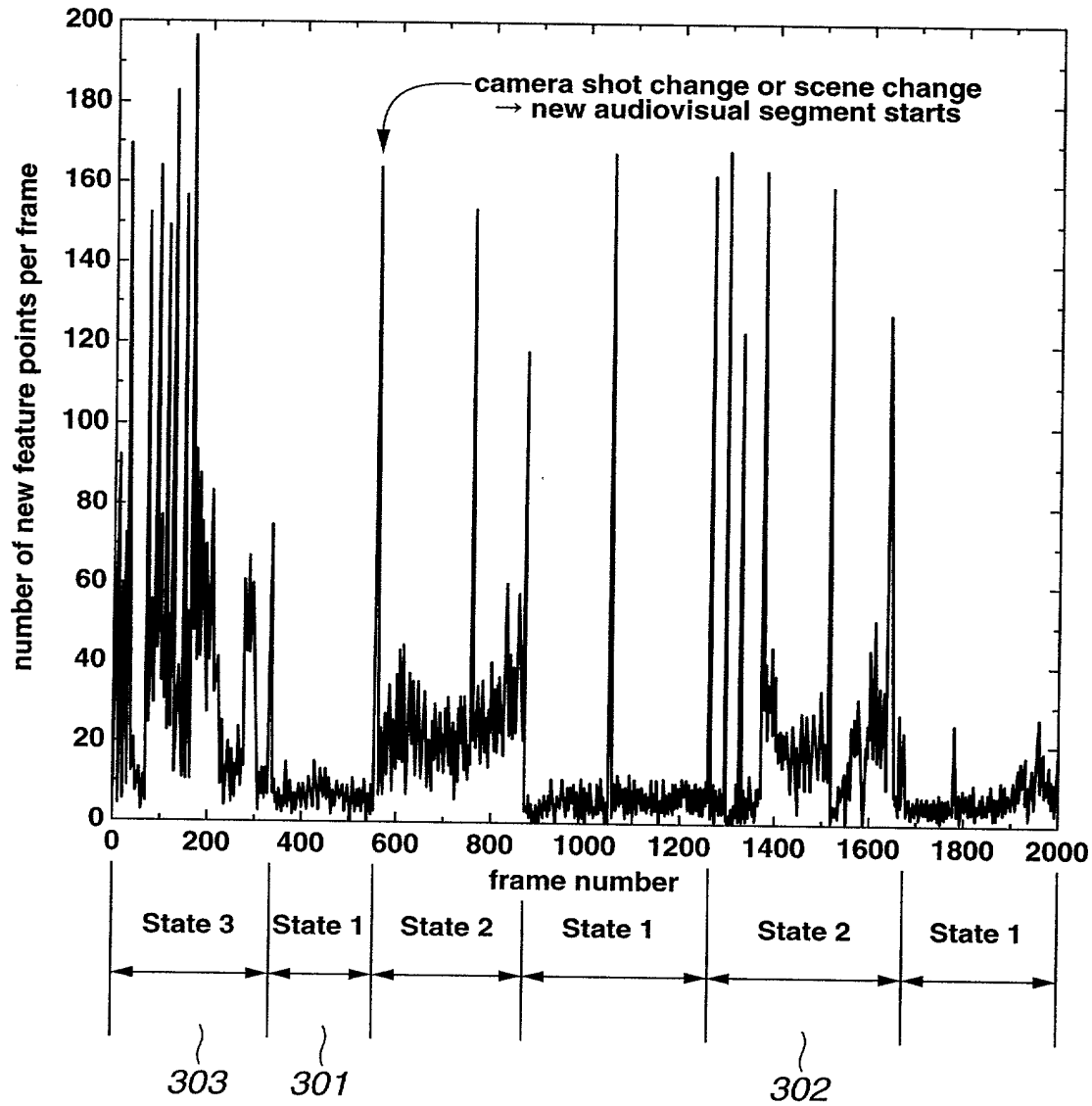


FIG.3

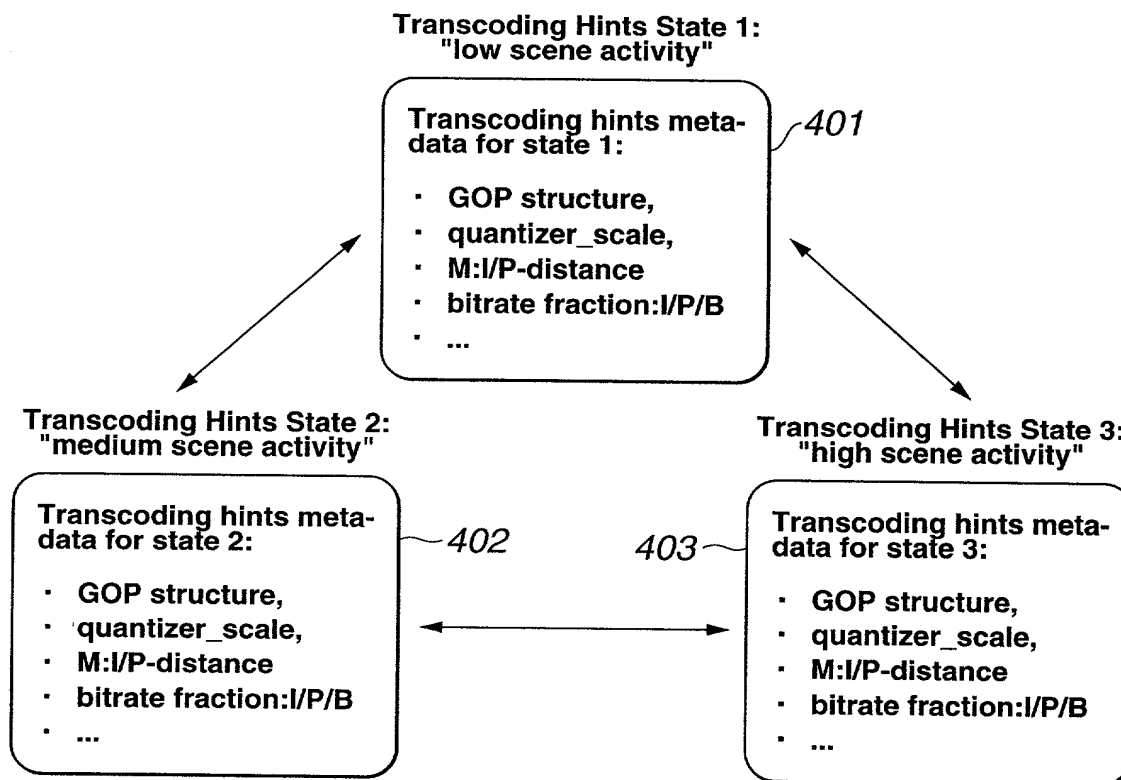


FIG.4

5/13

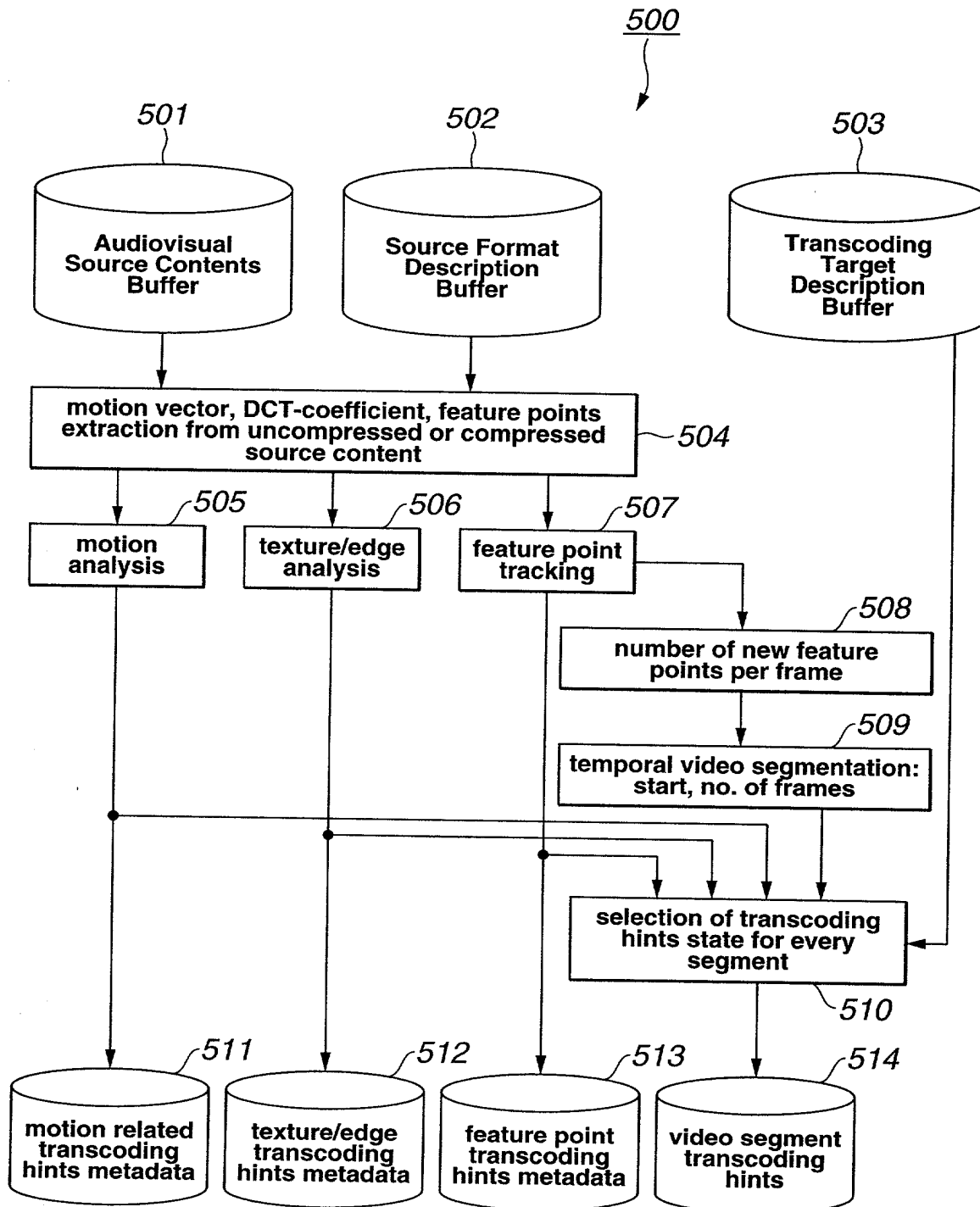


FIG.5

6/13

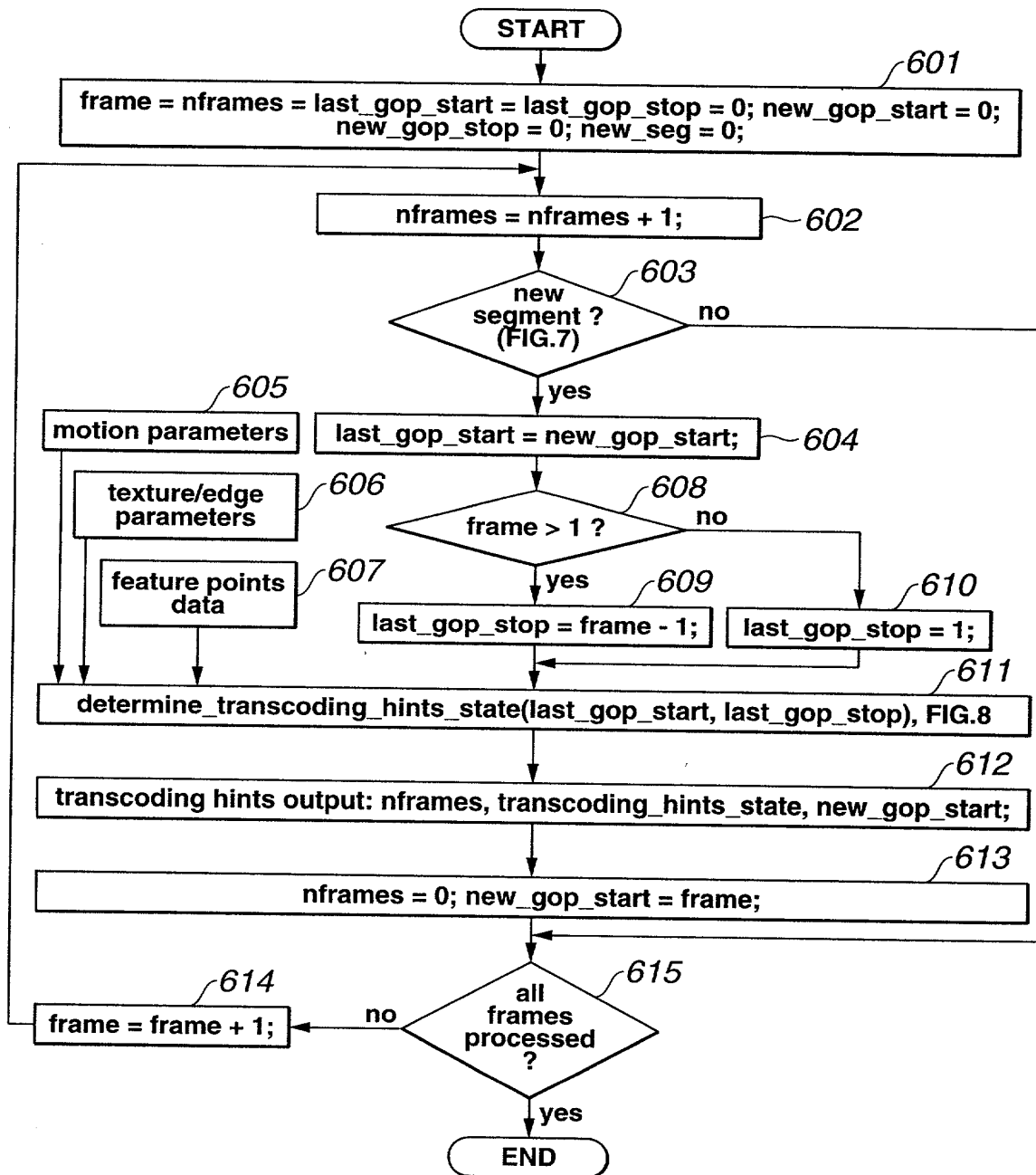


FIG.6

7/13

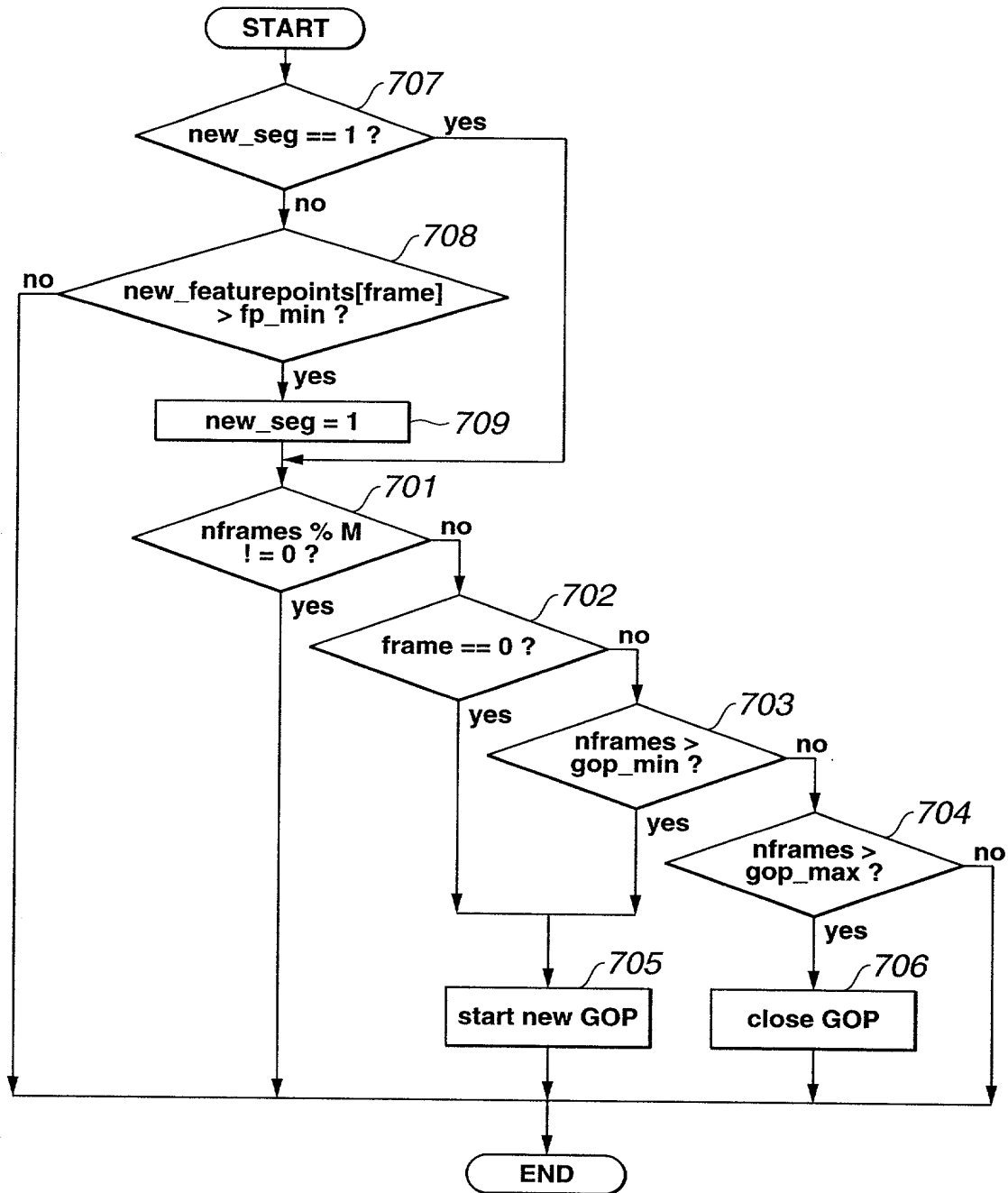


FIG. 7

8/13

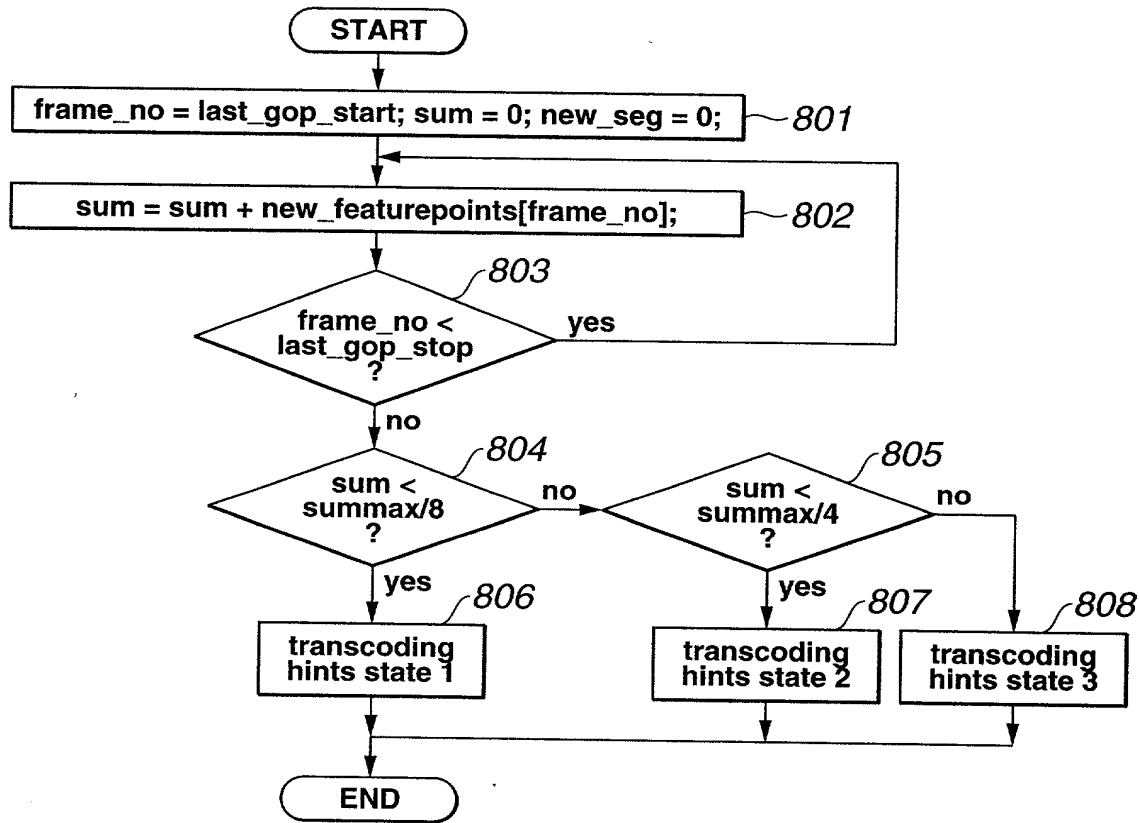


Table 1: Transcoding Hints State Table (example)

State	M	bitrate_fraction_for_l	bitrate_fraction_for_p
1	5	0.8	0.15
2	4	0.85	0.1
3	3	0.9	0.05

FIG.8



9/13

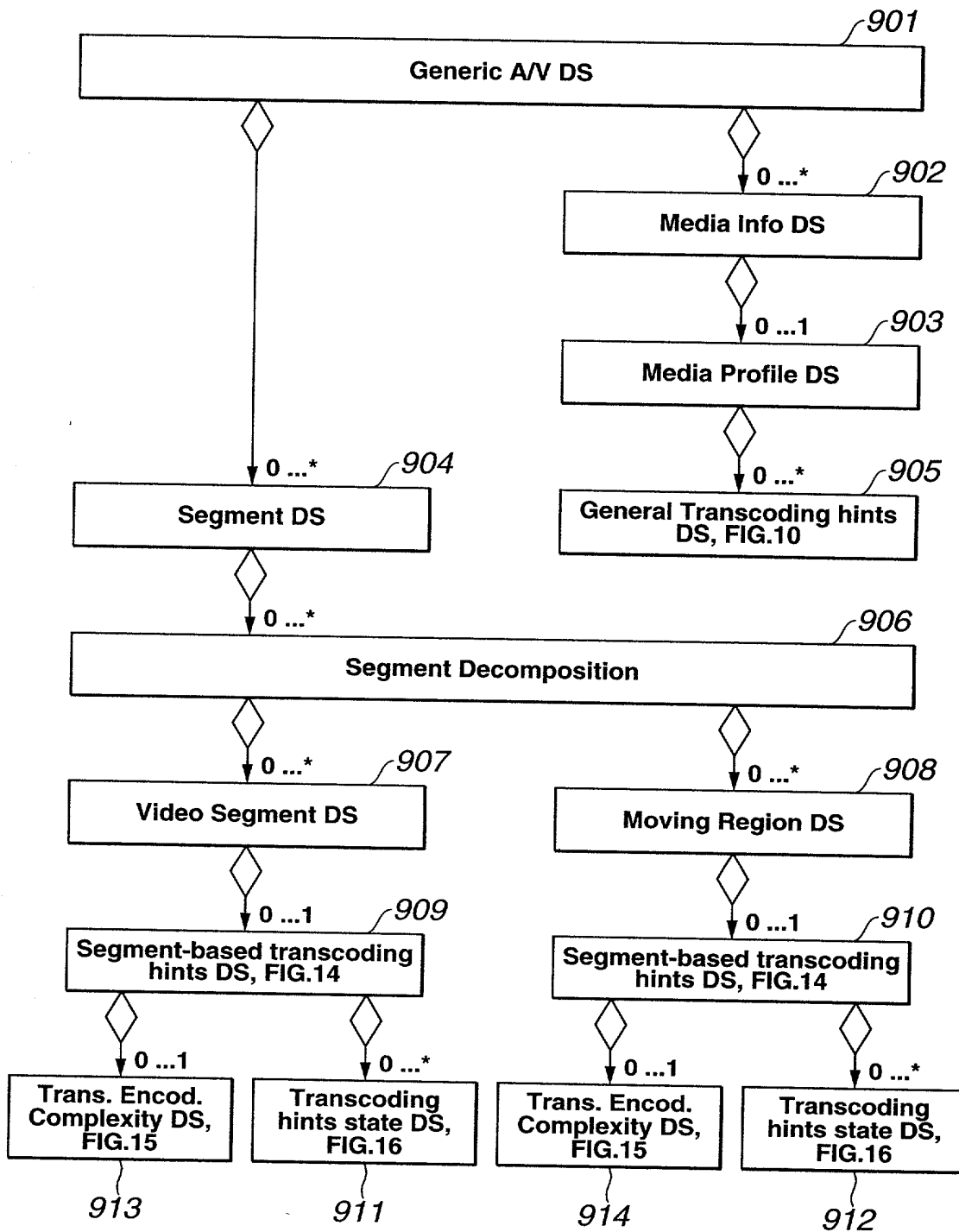
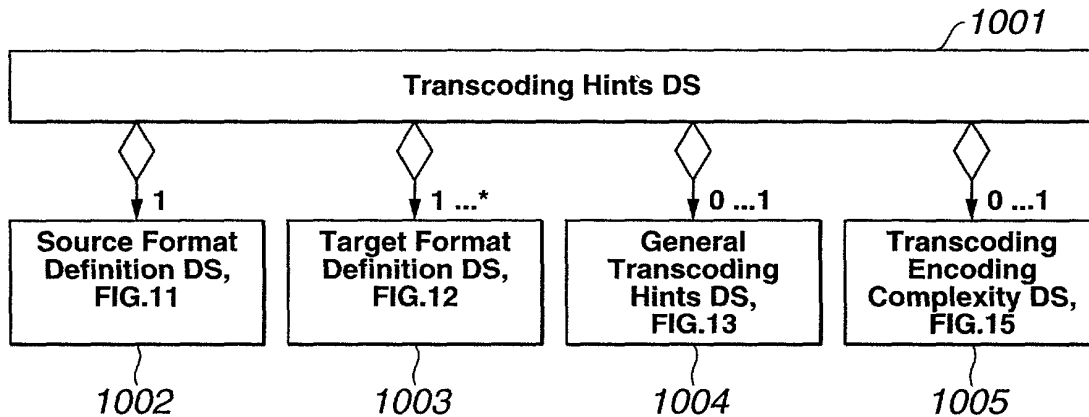


FIG. 9

10/13

**FIG.10**

- 1: bitrate <int>
- 2: size\_of\_pictures <2\*int>
- 3: number\_of\_frames\_per\_second <int>
- 4: pel\_aspect\_ratio <float>
- 5: pel\_colour\_depth <int>
- 6: usage\_of\_progressive\_interlaced\_format <1 bit>
- 7: usage\_of\_frame\_field\_pictures <1bit>
- 8: compression method <int>
- 9: one out of list {MPEG-1, MPEG-2, MPEG-4, DV, H.263, H.261, .... }
- 10: { further parameters for compression method }
- 11: GOP\_structure (Runlength coding)

**FIG.11**

11/13

- 1: bitrate <int>
- 2: size\_of\_pictures <2\*int>
- 3: number\_of\_frames\_per\_second <int>
- 4: pel\_aspect\_ratio <float>
- 5: pel\_colour\_depth <int>
- 6: usage\_of\_progressive\_interlaced\_format <1 bit>
- 7: usage\_of\_frame\_field\_pictures <1bit>
- 8: compression\_method <int>
- 9:       one\_out\_of\_list {MPEG-1, MPEG-2, MPEG-4, DV, H.263, H.261, .... }
- 10:       { further parameters for compression method }
- 11:       GOP\_structure (Runlength coding)

FIG.12

- 1: use\_region\_of\_interest\_DS: <1bit>
- 2:       region\_of\_interest\_DS:
- 3:       shape\_D: select one or {boundary\_box\_D, MB\_shape\_D, shape\_D}
- 4:       motion\_trajectory\_D
- 5:
- 6: use\_editing\_effects\_transcoding\_hints\_DS: <1bit>
- 7:       camera\_flash {frame1, frame2, .... framek} <k\*int>
- 8:       cross\_fading {(start\_frame, end\_frame), ... } <k\*(<int>, <int>)>
- 9:       black\_pictures {(start\_frame, end\_frame), ... } <k\*(<int>, <int>)>
- 10:       fade\_in {(start\_frame, end\_frame), ... } <k\*(<int>, <int>)>
- 11:       fade\_out {(start\_frame, end\_frame), ... } <k\*(<int>, <int>)>
- 12:       abrupt\_change {frame1, frame2, .... framek} <k\*int>
- 13:
- 14: use\_motion\_transcoding\_hints\_DS: <1 bit>
- 15:       number\_of\_regions: <int>
- 16:       for\_every\_region:
- 17:           is\_region\_rectangular\_shaped (y/n) : <1bit>
- 18:           if\_arbitrarily\_shaped: use region D for this region
- 19:           describe parametric object motion for this region

FIG.13

- 1: start\_frame <int>
- 2: nframes <int>
- 3: I\_frame\_location:
- 4:       select\_one\_out\_of\_the\_following: <2 bit>
- 5:       first frame (default)
- 6:       list of frames {frame1, frame2, . . . . , framek} <k\*int>
- 7:       first\_frame\_and\_every\_k\_frames <int>
- 8:       no\_I\_frame
- 9: quantizer\_scale <int>
- 10: target\_bitrate <int>
- 11: target\_min\_bitrate <int>
- 12: target\_max\_bitrate <int>
- 13: use\_transcoding\_states (y/n) <1 bit>
- 14: transcoding\_state\_nr <int>
- 15: add\_new\_transcoding\_state (y/n) <1bit>
- 16:       if yes: {list of parameters}
- 17: remove\_transcoding\_state (y/n) <1bit>
- 18:       if yes: state\_nr <int>
- 19: use\_encoding\_complexity\_description (y/n) <1 bit>
- 20:       if yes: encoding\_complexity\_description\_scheme

FIG.14

13/13

- 1: use\_feature\_points (y/n) <1bit>
- 2:     select\_feature\_point\_method <2 bits>
- 3:         number\_of\_new\_feature\_points <nframes \* int>
- 4:         feature\_point\_metrics {mean, max, min, var, stddev} <5\* int>
- 5: use\_equation\_description (y/n) <1bit>
- 6: use\_motion\_description (y/n) <1bit>
- 7:     select\_motion\_method <4 bits>
- 8:         param\_k\_motion <nframes \* k \* int>
- 9:         motion\_metrics {min, max, sum, var, stddev} <5\*int>
- 10:         block\_motion\_field < nframes\*int\*size\_x\*size\_y / (m\*m) >
- 11: use\_texture\_edge\_metrics (y/n) <1bit>
- 12:     select\_texture\_edge\_metrics <4 bits>
- 13:         DCT\_block\_energy <size\_y\*size\_x\*nframes\*int/64>
- 14:         DCT\_block\_activity <size\_y\*size\_x\*nframes\*int/64>
- 15:         DCT\_energy\_metric {mean, min, max, sum, var, stddev} <6\*int>
- 16:         DCT\_activity\_metric {mean, min, max, sum, var, stddev} <6\*int>

FIG.15

- 1: M: I/P distance <int>
- 2: bitrate\_fraction\_for\_I <float>
- 3: bitrate\_fraction\_for\_P <float> /\* bitrate\_fraction of B is rest to 100 %)
- 4: quantizer\_scale\_ratio\_I\_P <float>
- 5: quantizer\_scale\_ratio\_I\_B <float>
- 6: if\_frame: /\* see target format transcoding hints \*/
- 7:     X\_I, X\_P, X\_B <3\*int> /\* frame\_vbv\_complexities \*/
- 8: if\_field:
- 9:     X\_I\_top, X\_P\_top, X\_B\_top <3\*int> /\* field\_top\_vbv\_complexities \*/
- 10:     X\_I\_bot, X\_P\_bot, X\_B\_bot <3\*int> /\* field\_bottom\_vbv\_complexities \*/

FIG.16